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<p>(51) International classification :A61H 010000, A61H 010200, A61H 030000, A63B 210000, C11B 090000</p> <p>(86) International Application No :PCT// Filing Date :01/01/1900</p> <p>(87) International Publication No : NA</p> <p>(61) Patent of Addition to Application Number :NA Filing Date :NA</p> <p>(62) Divisional to Application Number :NA Filing Date :NA</p>	<p>(71)Name of Applicant : 1)Dr.S.Suganthi Address of Applicant :Assistant Professor, Department of Computer Science, G.Venkataswamy Naidu College (Autonomous), Kovilpatti, Thoothukudi, Tamil Nadu ----- -----</p> <p>2)Dr.G.Chelladurai 3)Dr. J Nelson Samuel Jebastin 4)Mrs.S.Indira Name of Applicant : NA Address of Applicant : NA</p> <p>(72)Name of Inventor : 1)Dr.S.Suganthi Address of Applicant :Assistant Professor, Department of Computer Science, G.Venkataswamy Naidu College (Autonomous), Kovilpatti, Thoothukudi, Tamil Nadu ----- -----</p> <p>2)Dr.G.Chelladurai Address of Applicant :Assistant Professor, Department of Zoology, G.Venkataswamy Naidu College (Autonomous), Kovilpatti, Thoothukudi, Tamil Nadu ----- -----</p> <p>3)Dr. J Nelson Samuel Jebastin Address of Applicant :Assistant Professor in Bioinformatics, Department of Zoology, Annamalai University, Annamalainagar, Tamil Nadu ----- -----</p> <p>4)Mrs.S.Indira Address of Applicant :Assistant Professor, Department of Computer Science, G.Venkataswamy Naidu College (Autonomous), Kovilpatti, Thoothukudi, Tamil Nadu ----- -----</p>
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(57) Abstract :

[048] The present invention relates to a new design developed in a robot for helping post stroke rehabilitation patients. The present invention is highly efficient, cost-effective. One of the primary benefits is that the robot device ensures that the movement is repeated in exactly the same way each time, which is critical for retraining the brain to enable muscles to carry out the movements independently. This consistency can be challenging for human therapists to achieve, especially during long rehabilitation sessions. This repetition is essential for building and strengthening neural connections, which can improve overall functional outcomes. The current invention robots can also collect data on the patient's performance, such as range of motion, speed, and force, providing more detailed and accurate information for therapists and doctors to assess progress. This feedback enables therapists to adjust the rehabilitation program accordingly and tailor it to the individual's needs, improving the chances of successful rehabilitation outcomes. The assistive and resistive training modality is designed and implemented in a robot which is an effective complement to traditional therapy methods, providing consistent, high-quality movement training and objective performance data to optimize the rehabilitation process. Accompanied Drawings [FIG.1-3]

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